

FIG. 1A

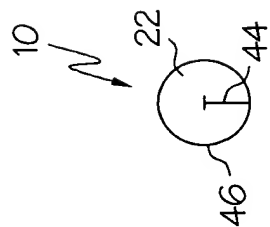


FIG. 1B

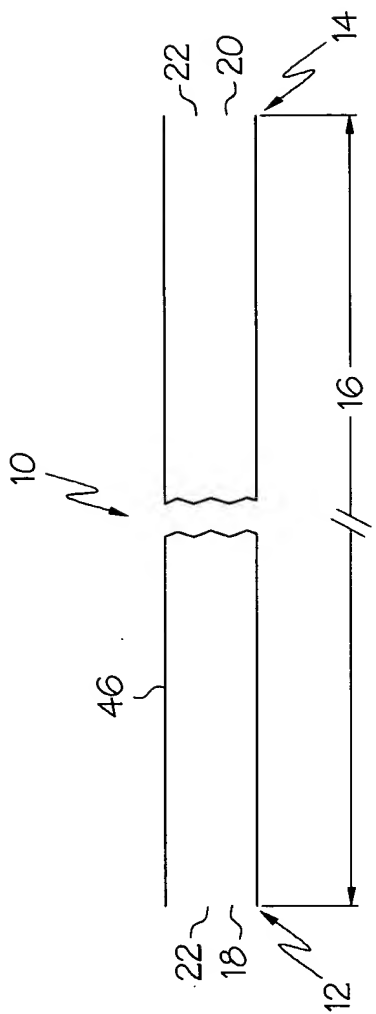


FIG. 1C

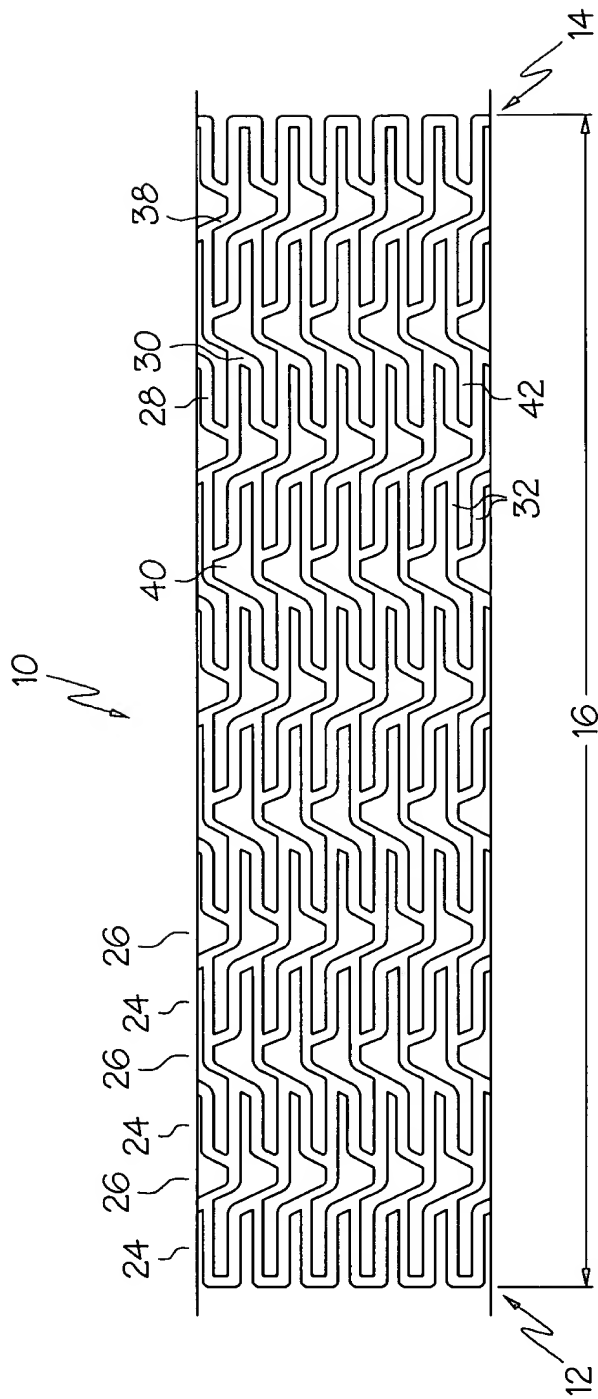


FIG. 2A

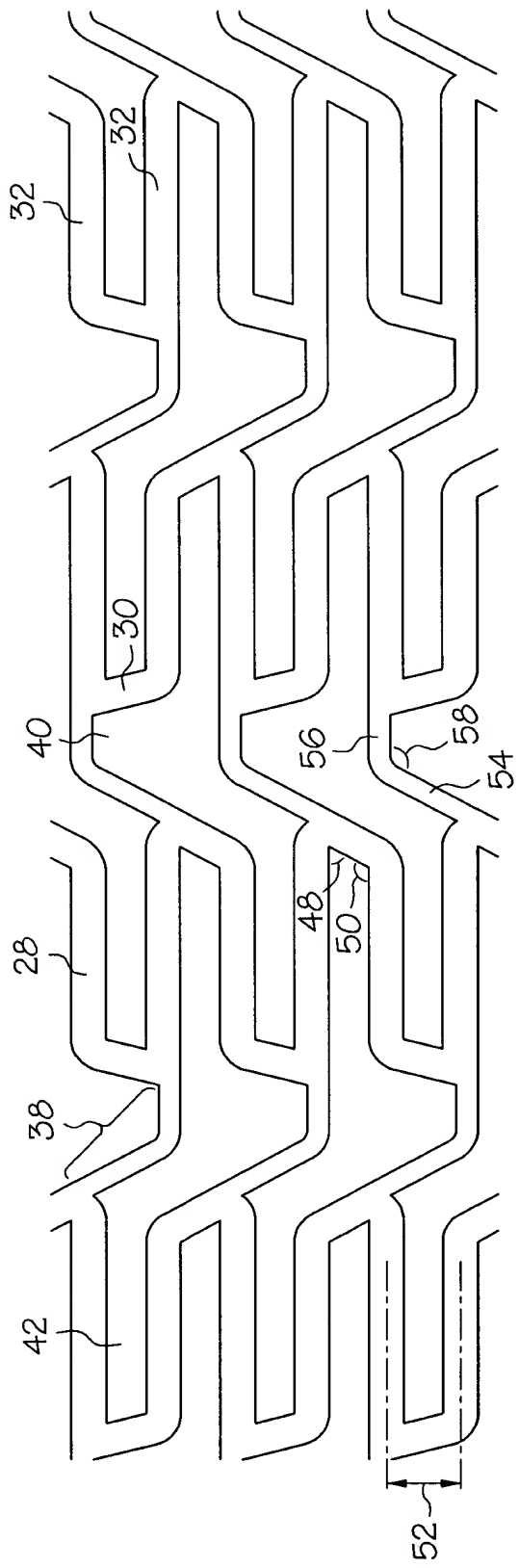


FIG. 2B

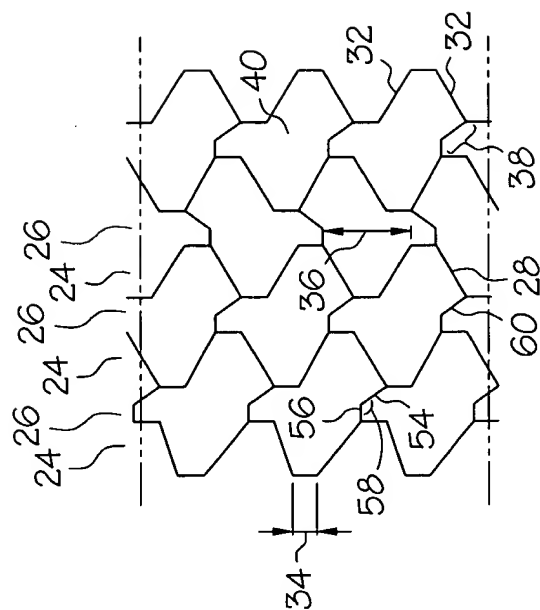


FIG. 3A

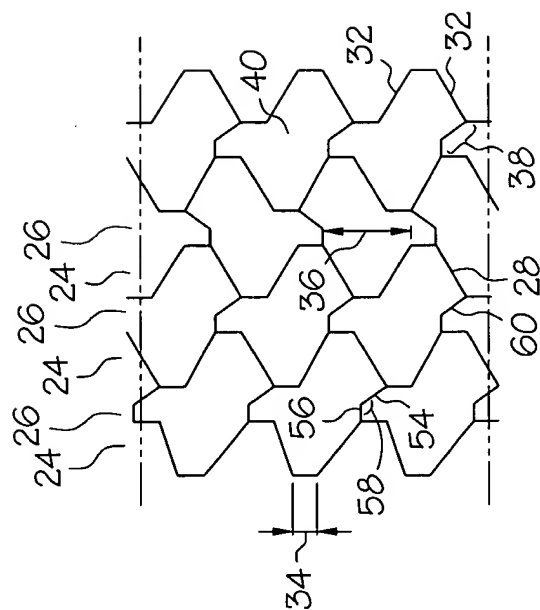
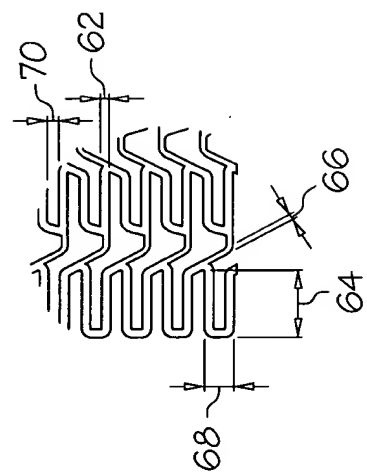
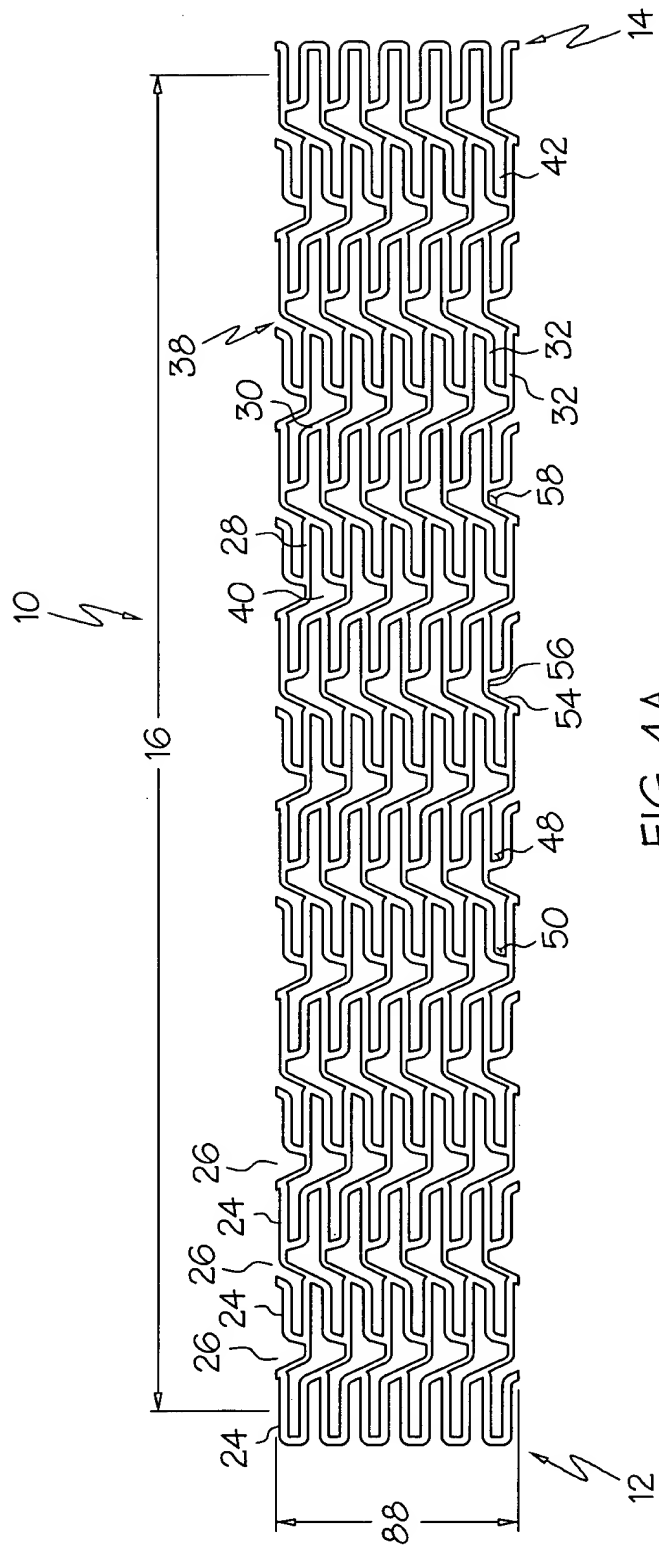


FIG. 3B



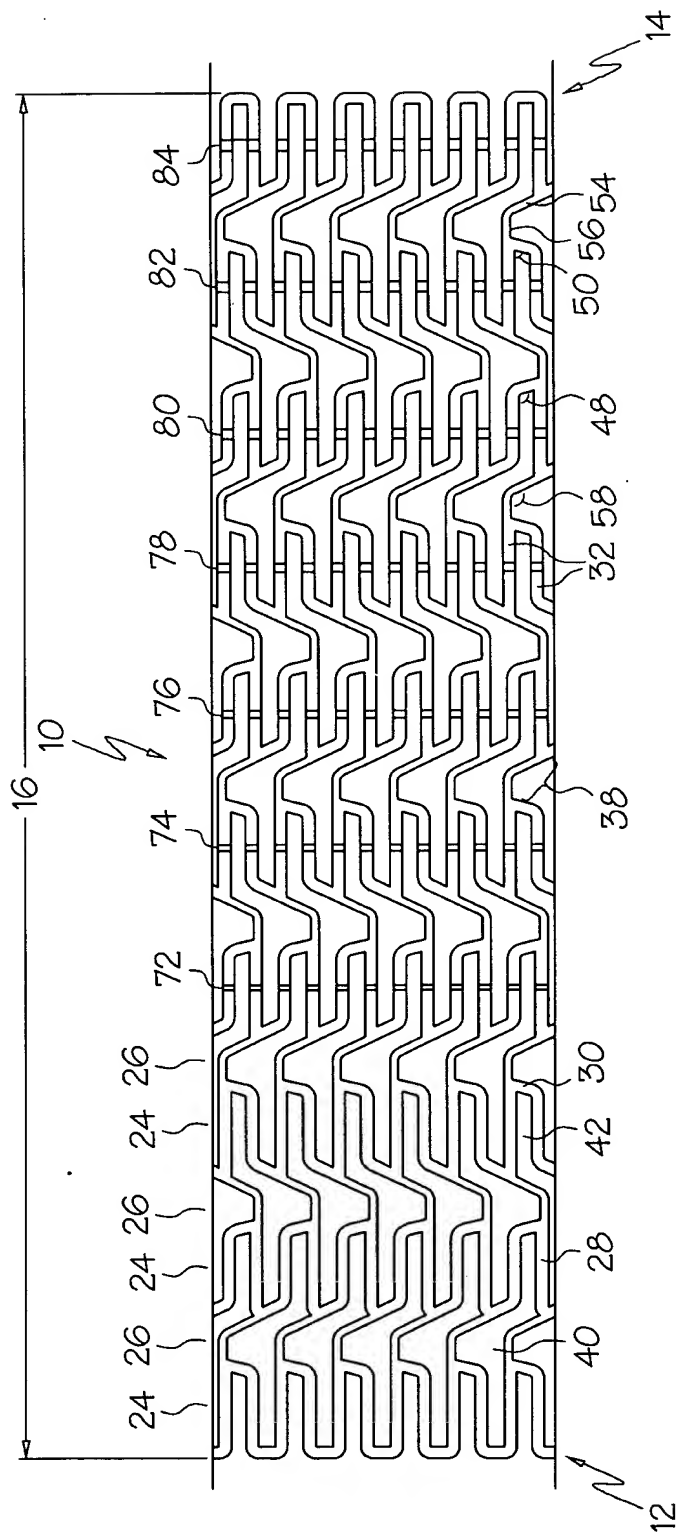


FIG. 5

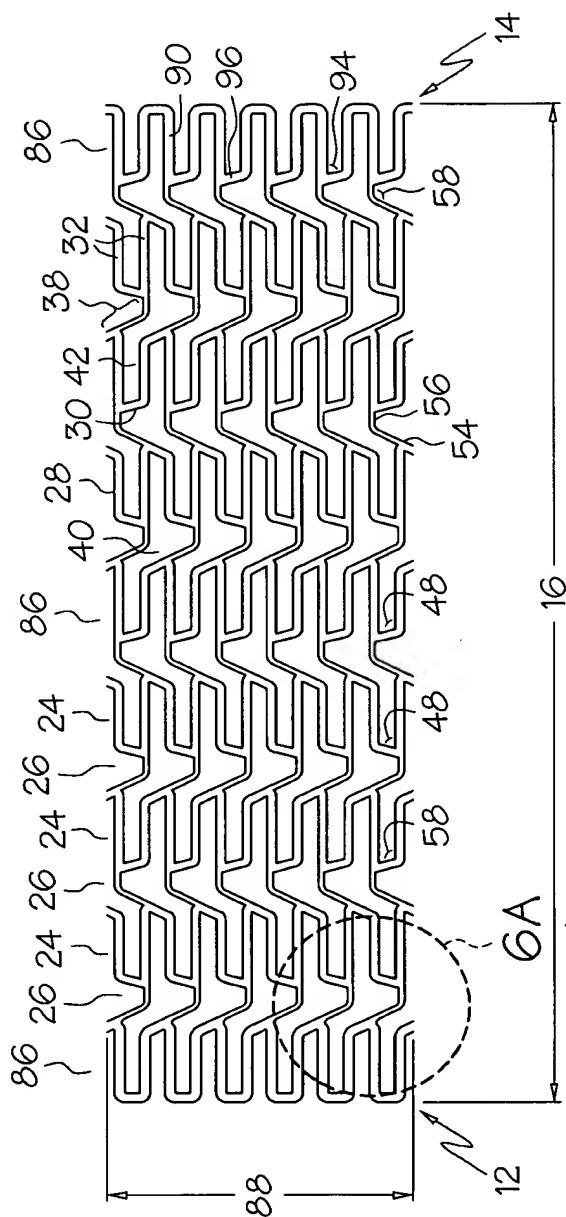


FIG. 6

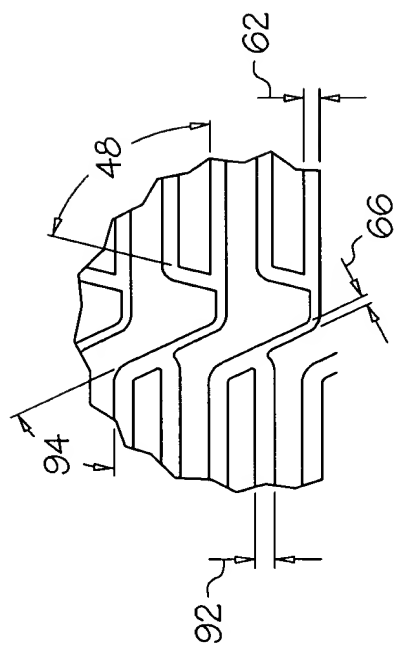


FIG. 6A

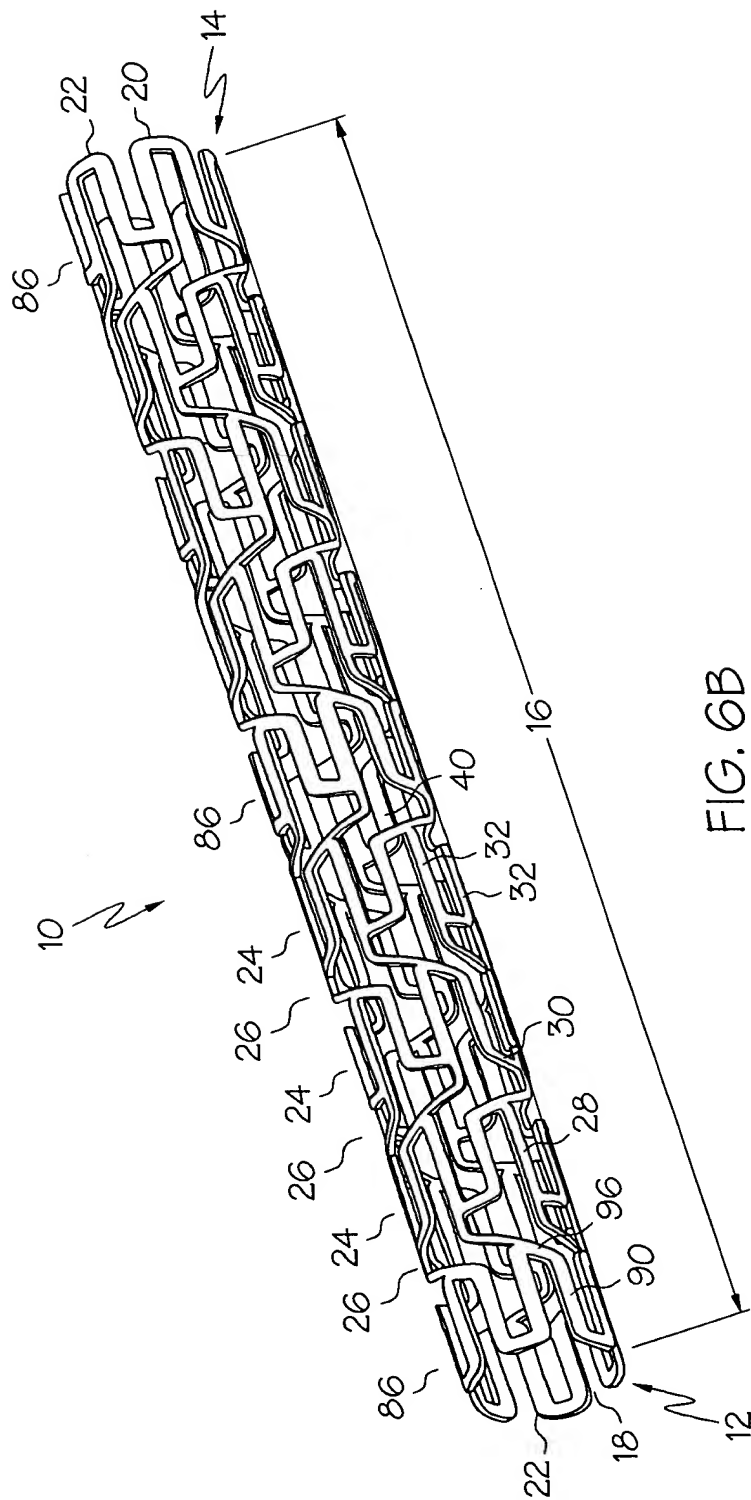


FIG. 6B

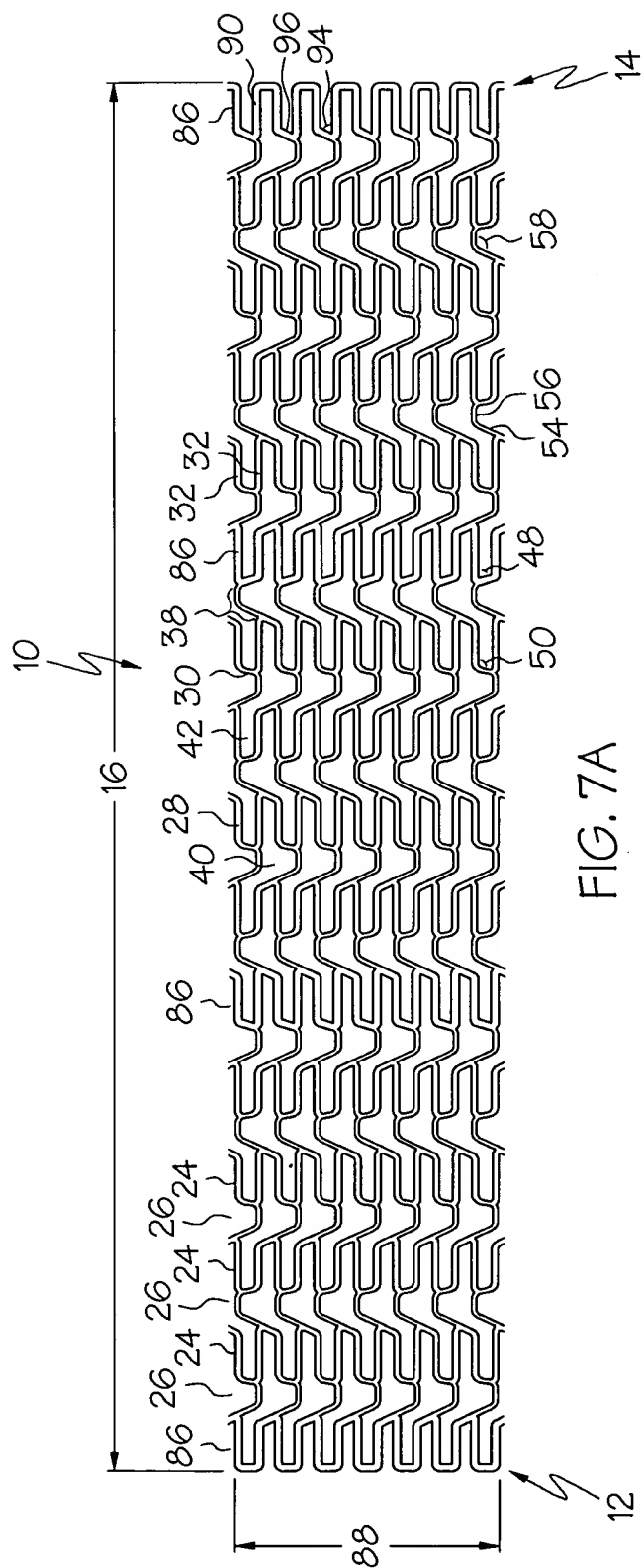
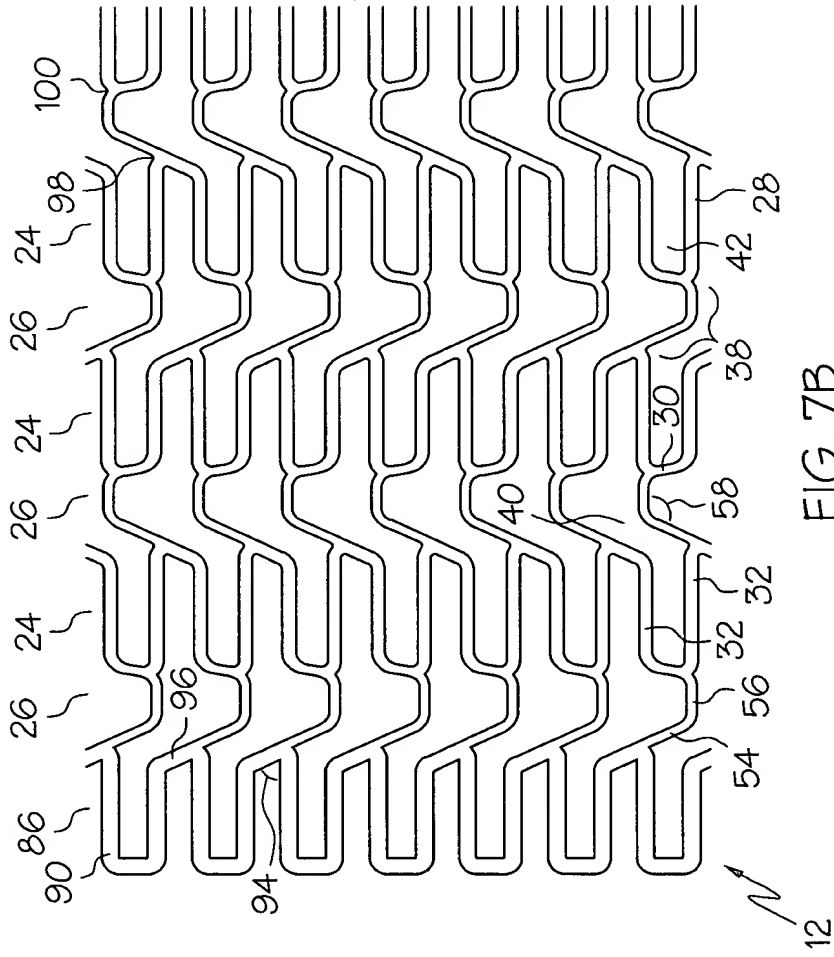


FIG. 7A



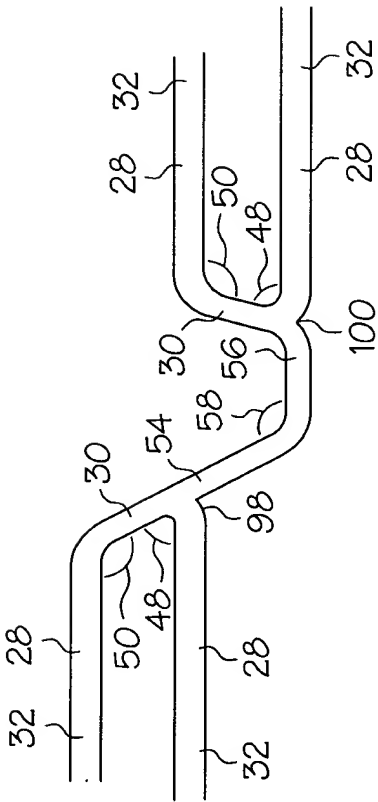


FIG. 7C

1. The first group of people who are not in the majority are those who are not in the majority.

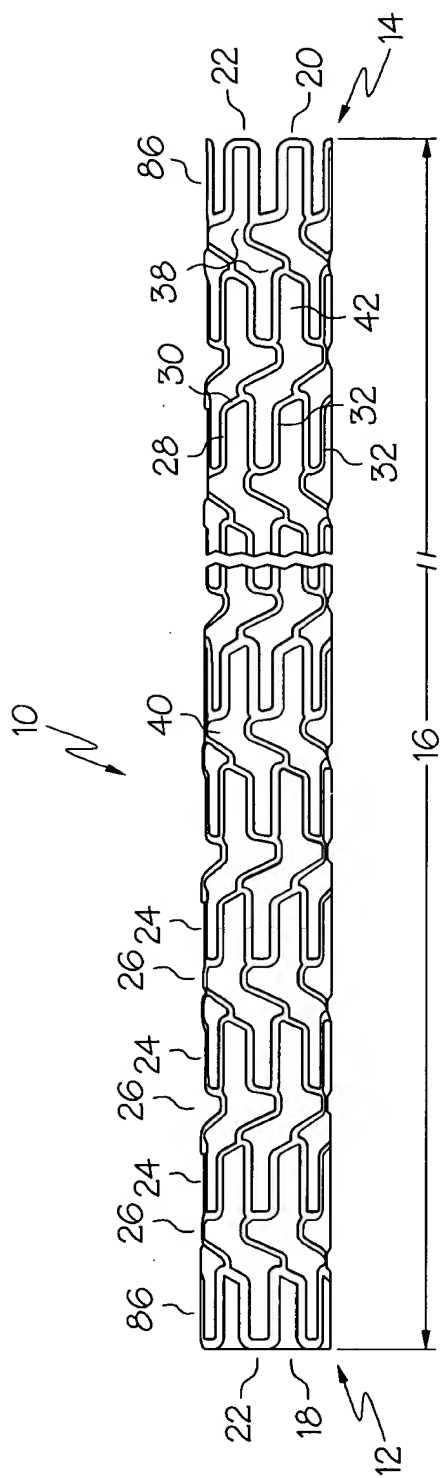


FIG. 8A

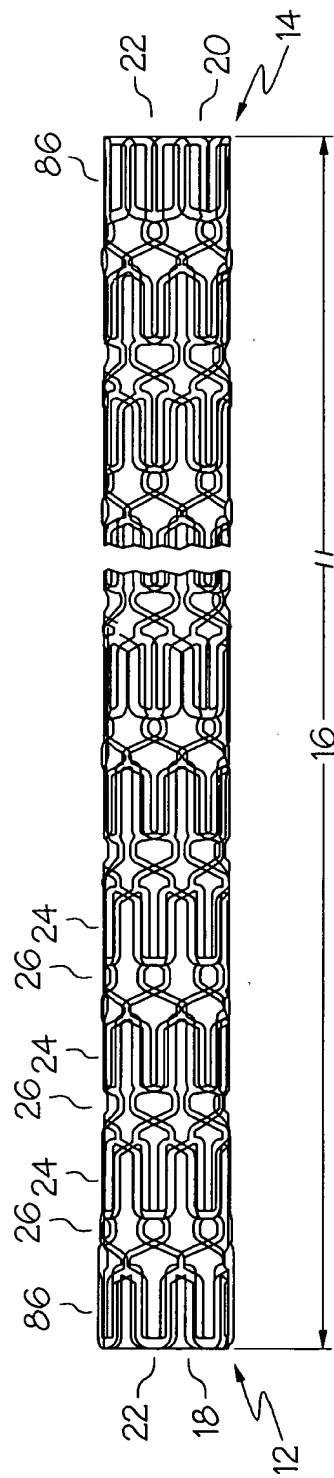


FIG. 8B

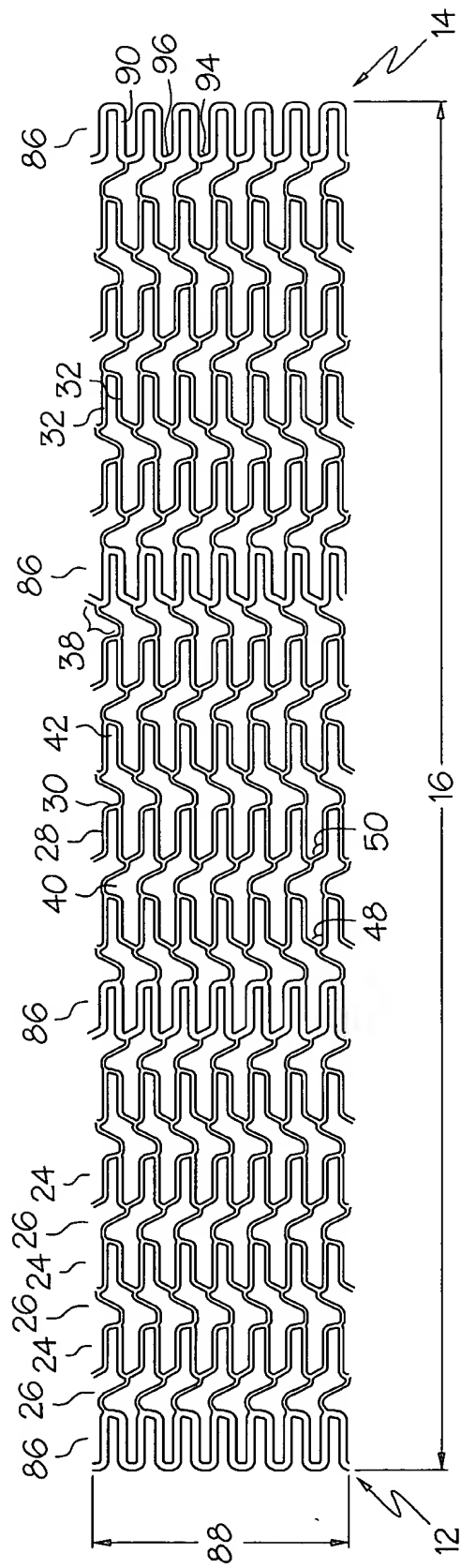


FIG. 8C

FIG. 8D

FIG. 8E is a perspective view of a portion of the elongated device 10. It shows the interlocking structure 14 and the longitudinal extent 16. The device 10 is shown in a perspective view, with the interlocking structure 14 and the longitudinal extent 16. The device 10 is shown in a perspective view, with the interlocking structure 14 and the longitudinal extent 16. The device 10 is shown in a perspective view, with the interlocking structure 14 and the longitudinal extent 16.

FIG. 8E

FIG. 9C is a perspective view of a second embodiment of a mesh structure. The mesh is composed of interconnected diamond-shaped cells. Labels include 12 and 14 for the edges, 24, 26, 28, 32, 36, 38, 40, 86, 90, and 96 for various structural features and joints.

FIG. 8F

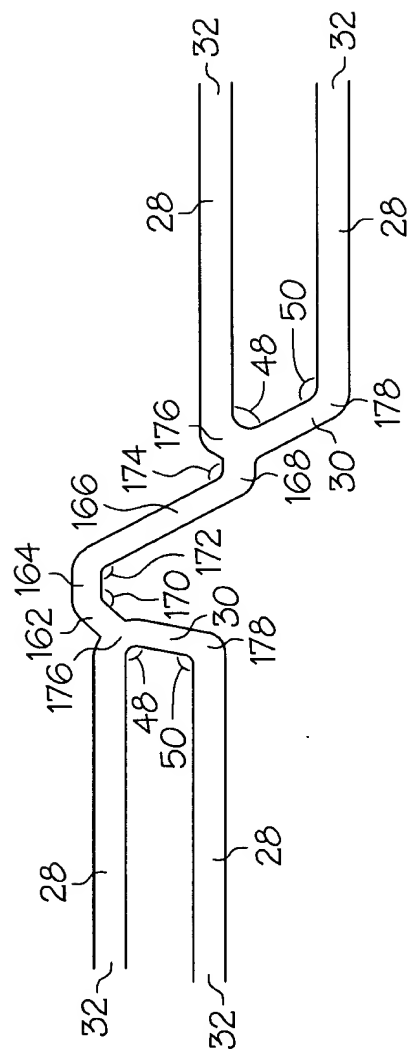
[illegible]

FIG. 8G

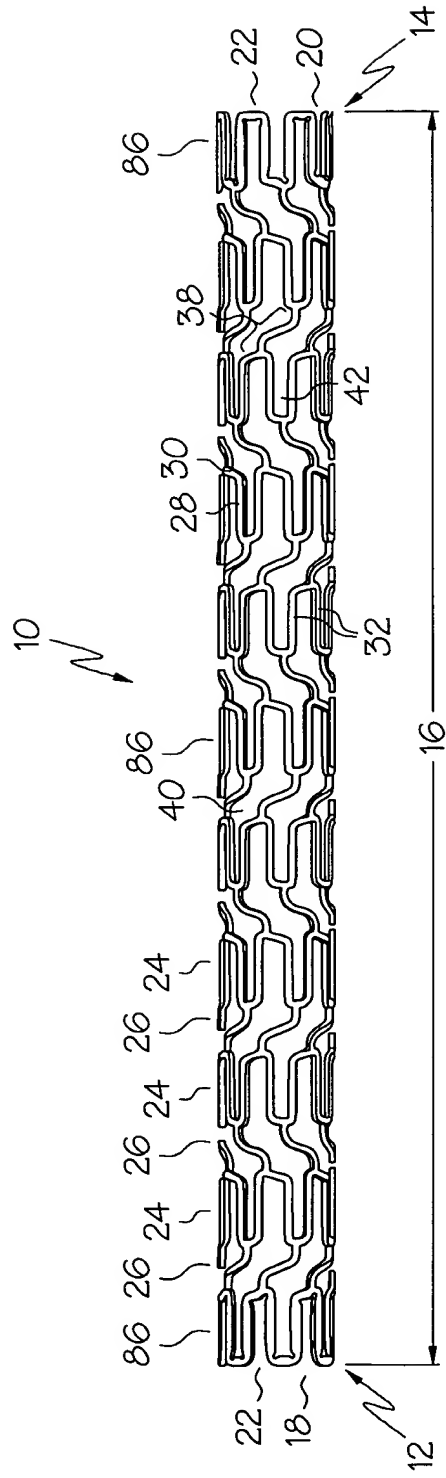


FIG. 9A

11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100

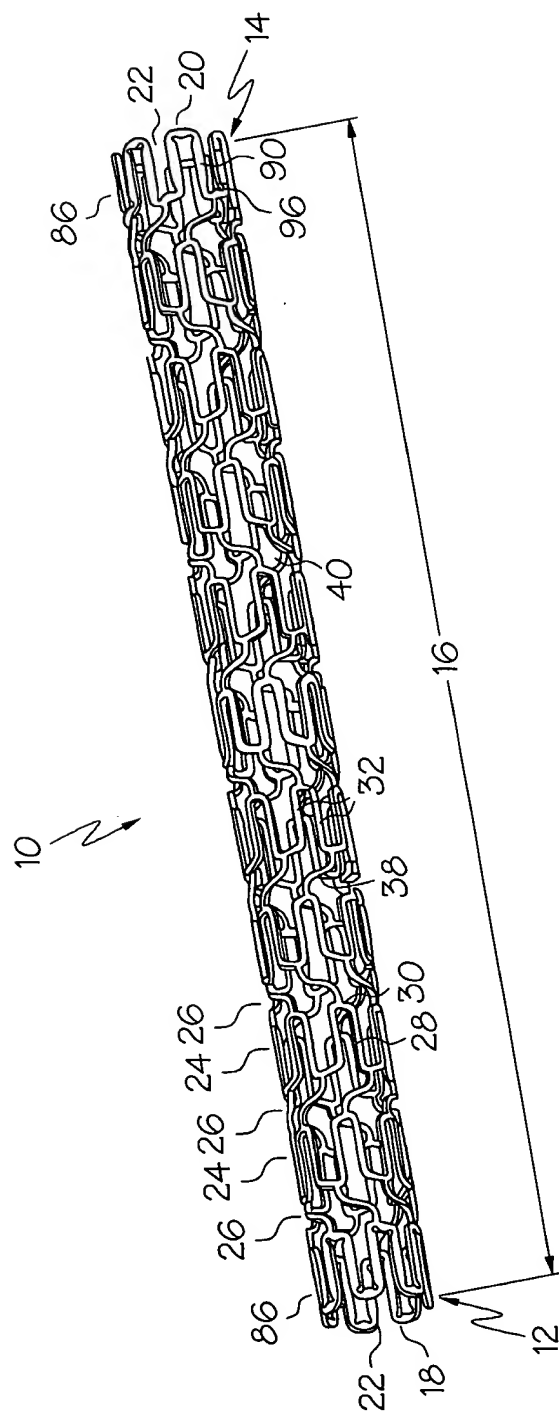


FIG. 9B

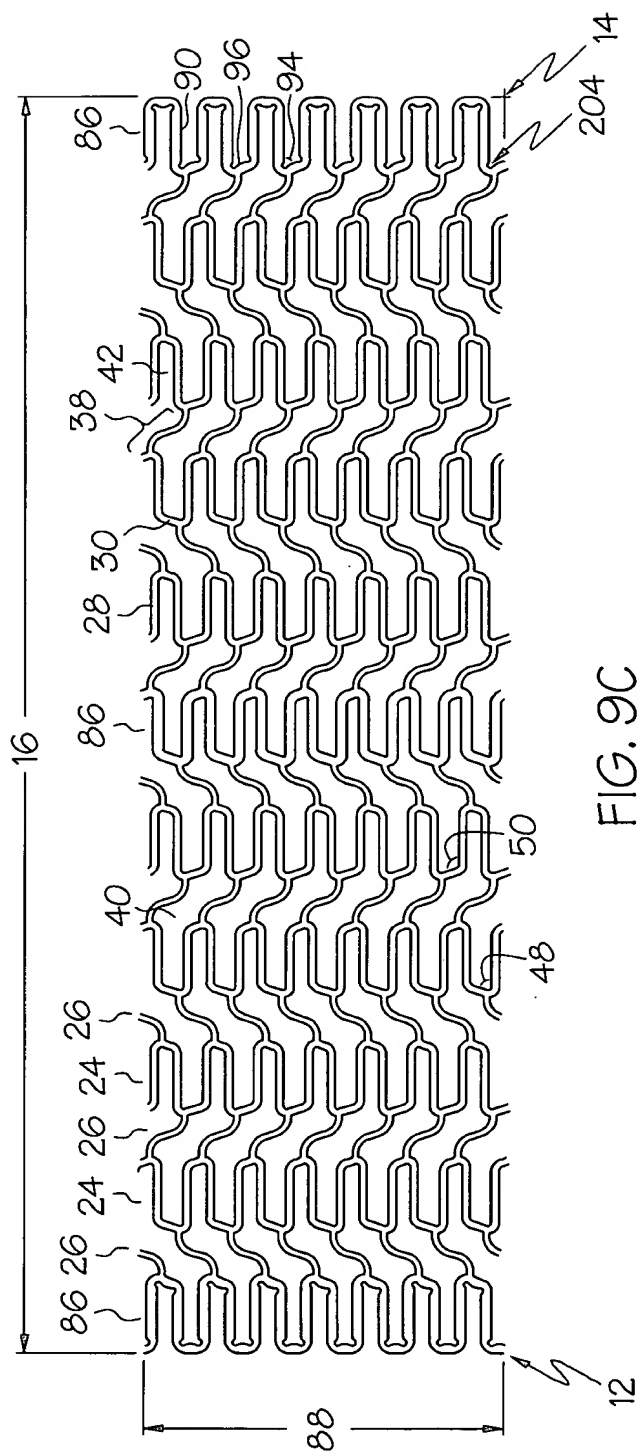
[illegible]

FIG. 9C

FIG. 9D

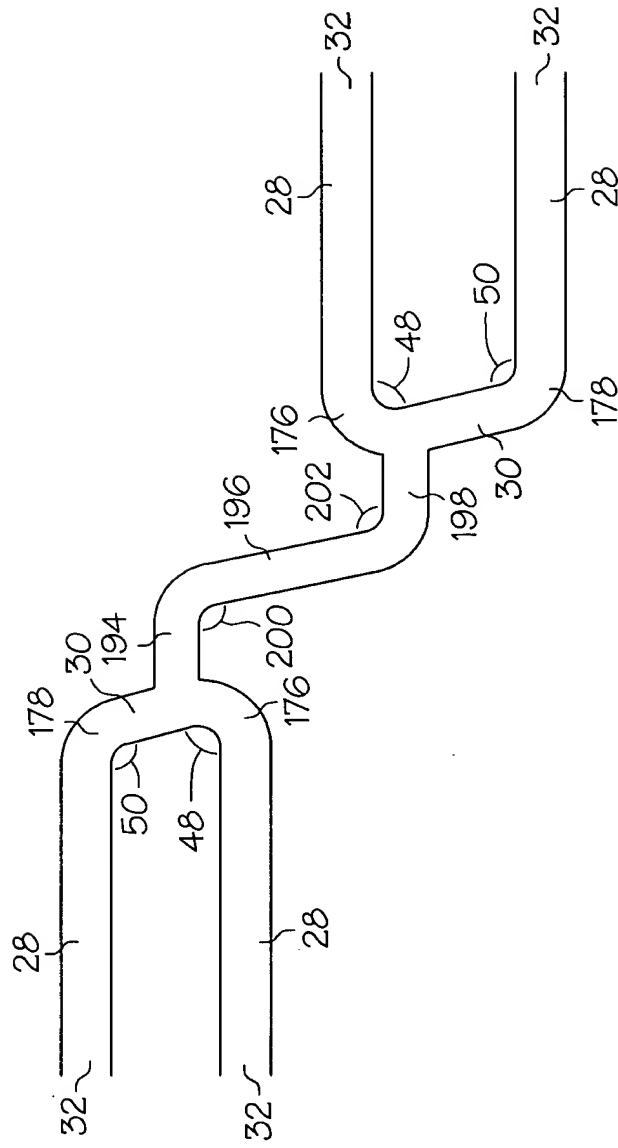


FIG. 9E

FIG. 9F is a perspective view of the mesh structure 10 of FIG. 9A, showing the mesh structure 10 in a folded state. The mesh structure 10 is formed by a plurality of interconnected, elongated, rectangular mesh elements 12, which are arranged in a grid pattern. The mesh elements 12 are interconnected by a plurality of horizontal and vertical lines 14, which form the mesh structure 10. The mesh structure 10 is shown in a folded state, with the mesh elements 12 and the horizontal and vertical lines 14 being visible. The mesh structure 10 is formed by a plurality of interconnected, elongated, rectangular mesh elements 12, which are arranged in a grid pattern. The mesh elements 12 are interconnected by a plurality of horizontal and vertical lines 14, which form the mesh structure 10. The mesh structure 10 is shown in a folded state, with the mesh elements 12 and the horizontal and vertical lines 14 being visible.

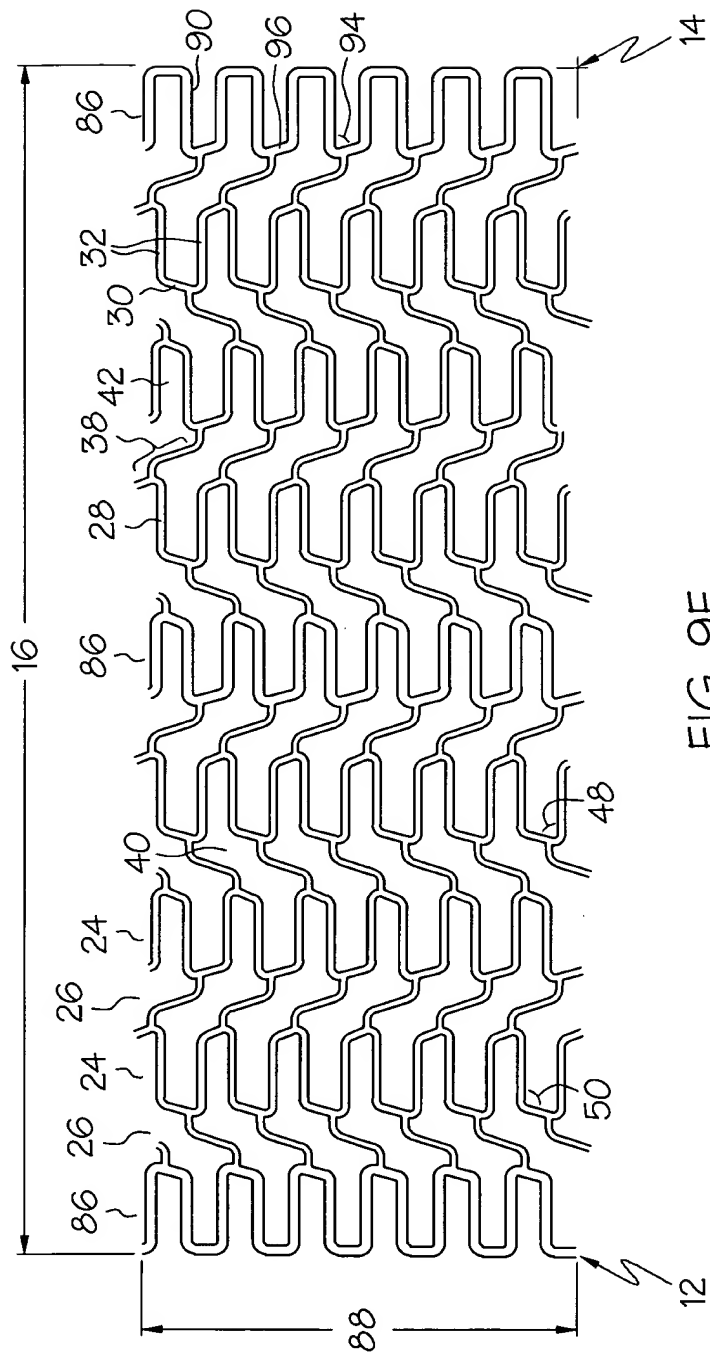


FIG. 9F

any other suitable means for providing a signal to the processor, such as a microphone, a camera, a sensor, or the like.

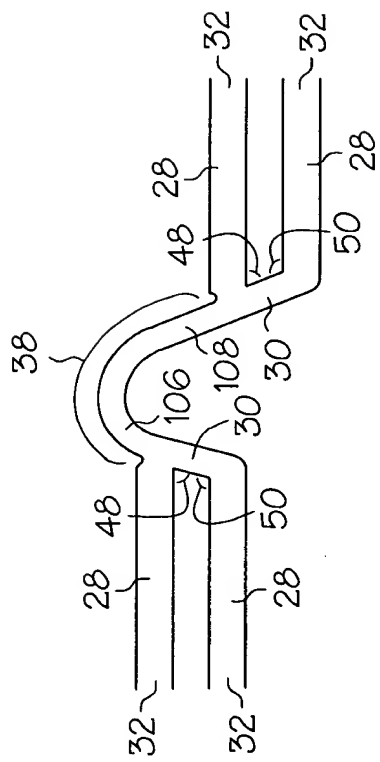


FIG. 10A

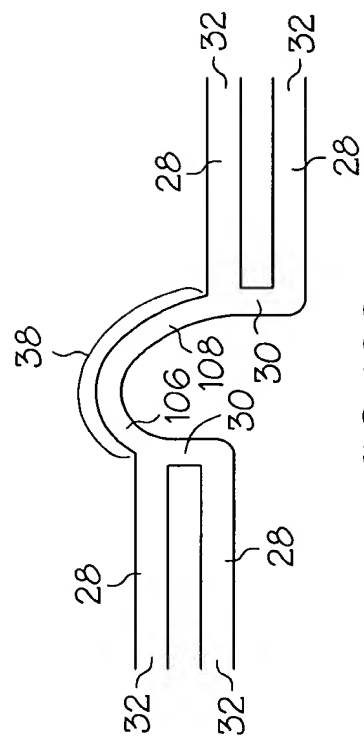


FIG. 10B

1. The first step is to identify the problem. This involves understanding the symptoms and the context in which they are occurring.

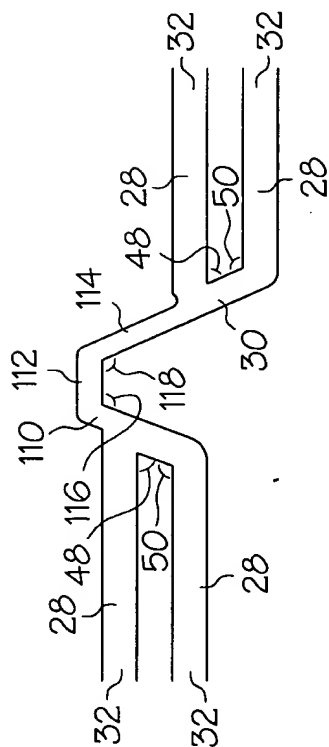


FIG. 10C

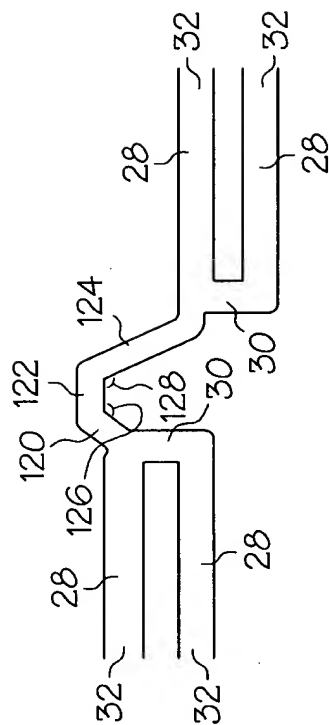


FIG. 10D

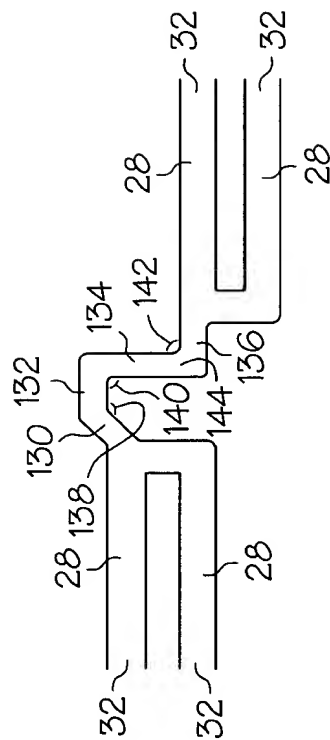


FIG. 10E

FIG. 10F is a cross-sectional view of the device 100 taken along line 100-100F of FIG. 10E. The device 100 includes a central shaft 10, a proximal handle 12, and a distal tip 14. The proximal handle 12 includes a proximal grip 16 and a proximal control 18. The distal tip 14 includes a distal grip 20 and a distal control 22. The central shaft 10 includes a proximal section 24 and a distal section 26. The proximal section 24 includes a proximal grip 28 and a proximal control 30. The distal section 26 includes a distal grip 32 and a distal control 34. The proximal grip 28 and proximal control 30 are connected to the proximal grip 16 and proximal control 18, respectively. The distal grip 32 and distal control 34 are connected to the distal grip 20 and distal control 22, respectively. The central shaft 10 is configured to provide a stable and secure connection between the proximal and distal sections.

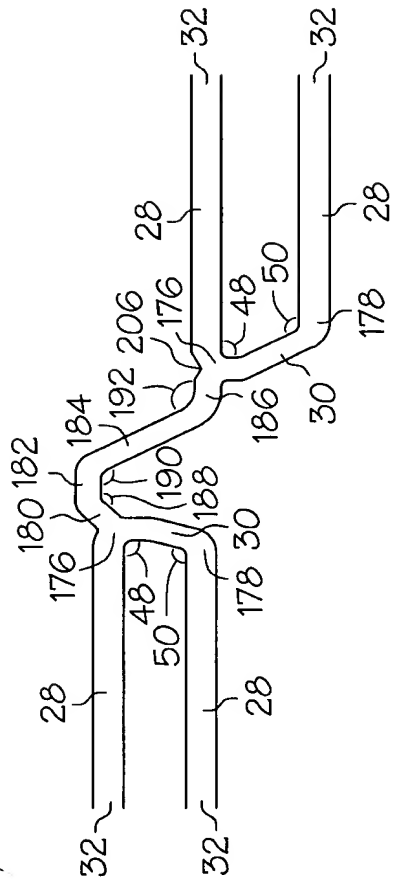


FIG. 10F

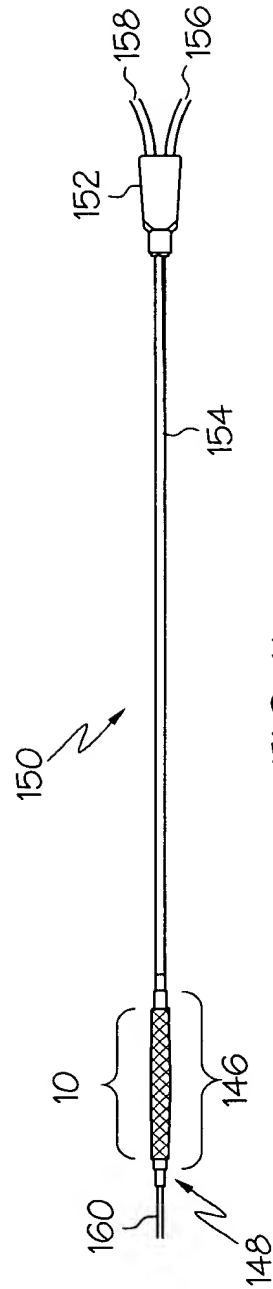


FIG. 11